

Runge - Kutta methods of order 2

→ (Midpoint method)

Recall :

Taylor methods of order 2 :

$$\{ w_0 = \alpha$$

$$w_{i+1} = w_i + h T^{(2)}(t_i, w_i)$$

$$f(t_i, w_i) + \frac{h}{2} f'(t_i, w_i)$$

$$(\text{error} = O(h^3))$$

Idea: Find $\alpha_1, \alpha_2, \beta_1$ s.t.

$$T^{(2)}(t_i, w_i) \approx \alpha_1 f(t + \alpha_1, y + \beta_1)$$

and error stays $O(h^3)$

The derivation requires 2 Ingredients

- Ingredient I \circ Taylor polynomials
for functions of 2 variables :

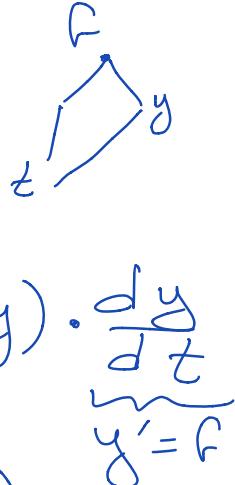
$$f(t+\alpha_1, y+\beta_1) = f(t, y) + [\alpha_1, \beta_1] \begin{bmatrix} \frac{\partial f}{\partial t} \\ \frac{\partial f}{\partial y} \end{bmatrix} \Big|_{(t, y)} + \frac{1}{2} [\alpha_1, \beta_1] \begin{bmatrix} \frac{\partial^2 f}{\partial t^2} & \frac{\partial^2 f}{\partial t \partial y} \\ \frac{\partial^2 f}{\partial t \partial y} & \frac{\partial^2 f}{\partial y^2} \end{bmatrix} \Big|_{(\bar{x}, \bar{y})} [\alpha_1, \beta_1]$$

error term \tilde{R}_1 or \tilde{E}_1
where (\bar{x}, \bar{y}) between (t, y) & $(t+\alpha_1, y+\beta_1)$

• Ingredient II: Chain Rule

$$F'(t, y) = \frac{df}{dt}(t, y(t))$$

$$= \frac{\partial f}{\partial t}(t, y) + \frac{\partial f}{\partial y}(t, y) \cdot \underbrace{\frac{dy}{dt}}_{y' = f}$$



but $T^{(2)}(t, y) = f(t, y) + \frac{h}{2}f'(t, y)$

so $\boxed{T^{(2)}(t, y) = f + \frac{h}{2} \left[\frac{\partial f}{\partial t} + \frac{\partial f}{\partial y} \cdot F \right]}$

Rewriting ① & multiplying it by a_1 :

$$\begin{aligned} a_1 f(t+\alpha_1, y+\beta_1) &= a_1 f(t, y) + a_1 \alpha_1 \frac{\partial f}{\partial t}(t, y) \\ &\quad + a_1 \beta_1 \frac{\partial f}{\partial y}(t, y) \end{aligned}$$

$$+ a_1 R_1$$

③

Since we want $\overline{T^{(2)}}(t, y) \approx a_1 f(t+\alpha_1, y+\beta_1)$

we just match coefficients of F ,

$\frac{\partial F}{\partial t}$ & $\frac{\partial F}{\partial y}$ in ② & ③ And we
solve for a_1, α_1, β_1 :

$$\Rightarrow \boxed{a_1 = 1}, \boxed{\frac{h}{2} = a_1 \alpha_1}, \boxed{\frac{h}{2} \cdot f(t, y) = a_1 \beta_1}$$

So now :

$$F\left(t + \frac{h}{2}, y + \frac{h}{2}F(t, y)\right) = T^{(2)}(t, y) + R_1\left(t + \frac{h}{2}, y + \frac{h}{2}F(t, y)\right)$$
$$\left[\begin{matrix} h/2 & h/2F(t, y) \end{matrix} \right] \left[\begin{matrix} \frac{\partial^2 F}{\partial t^2} & \frac{\partial^2 F}{\partial y \partial t} \\ \frac{\partial^2 F}{\partial t \partial y} & \frac{\partial^2 F}{\partial y^2} \end{matrix} \right] \left[\begin{matrix} h/2 \\ h/2F(t, y) \end{matrix} \right]$$

$\approx O(h^2)$ if all partials
are bounded.

\Rightarrow local error is $O(h^3)$

So we replace $T^{(2)}(t, y)$ by

$f(t + \frac{h}{2}, y + \frac{h}{2}f(t, y))$
to get :

$$\begin{cases} w_0 = d \\ w_{i+1} = w_i + h f\left(t_i + \frac{h}{2}, w_i + \frac{h}{2} f(t_i, w_i)\right) \end{cases}$$

for $i = 0, \dots, N-1$

→ Runge-Kutta method of order 2

also known as : Midpoint method

Another $O(h^3)$ method is given by

$$\begin{cases} w_0 = d \end{cases}$$

$$w_{i+1} = w_i + \frac{h}{2} [f(t_i, w_i) + f(t_{i+1}, w_i + h f(t_i, w_i))]$$



y' at (t_i, w_i)

est. of y'
at $(t_{i+1}, w_i + h f(t_i, w_i))$

\downarrow
1st order approx
of w_{i+1})

modified

Euler Method /
Heun's Method -

\approx Average of derivatives/slopes

Idea behind this modification:

$$w_i + h f(t_i, w_i) =: \tilde{w}_{i+1} \text{ is the}$$

estimate from Euler's method
of y_{i+1} .

Rather than use \tilde{w}_{i+1} directly,
we plug it back into

$$f(t_{i+1}, \tilde{w}_{i+1}) \approx \text{estimate of slope}
at t_{i+1}$$

and average it with $f(t_i, w_i)$,
to get

$$\left\{ \begin{array}{l} w_{i+1} = w_i + \frac{h}{2} [f(t_i, w_i) + f(t_{i+1}, \tilde{w}_{i+1})] \\ \text{where } \tilde{w}_{i+1} = w_i + h f(t_i, w_i) \end{array} \right.$$

General RK2 :

$$w_{i+1} = w_i + a_1 h f(t_i, w_i) + a_2 h f(t_i + \alpha, y + \beta)$$

Example of Higher order RK method

RK order 4 :

$$\left\{ \begin{array}{l} w_0 = \alpha \\ k_1 = h f(t_i, w_i) \\ k_2 = h f(t_i + \frac{h}{2}, w_i + \frac{1}{2}k_1) \\ k_3 = h f(t_i + \frac{h}{2}, \overbrace{w_i + \frac{1}{2}k_2}^{\text{est of } y \text{ at } t_i + \frac{h}{2}}) \\ k_4 = h f(\underline{t_i + h}, w_i + k_3) \\ w_{i+1} = w_i + \frac{1}{6}(k_1 + 2k_2 + 2k_3 + k_4) \end{array} \right.$$

Error = $O(h^5)$
(provided $y \in C^5$)

Summary of our numerical methods for IVP's :

$$\begin{cases} y' = f(t, y) , \quad t \in [a, b] \\ y(a) = \alpha \end{cases}$$

(I) Euler's method $O(h)$

$w_0 = \alpha$
 $w_{i+1} = w_i + hf(t_i, w_i)$

(II) Higher order Taylor methods $O(h^{n+1})$

$w_0 = \alpha$
 $w_{i+1} = w_i + h T^{(n)}(t_i, w_i)$

where $T^{(n)}(t_i, w_i) = f(t_i, w_i) + \frac{h}{2} f'(t_i, w_i)$

 $+ \frac{h^2}{6} f''(t_i, w_i) + \dots + \frac{h^{n-1}}{n!} f^{(n-1)}(t_i, w_i)$

(III) Runge-Kutta methods

(IIIa) Order 2 ($O(h^3)$)

$$w_0 = \alpha$$

$$w_{i+1} = w_i + h f\left(t_i + \frac{h}{2}, w_i + \frac{h}{2} f(t_i, w_i)\right)$$

(IIIb) Order 4 ($O(h^5)$)

(See before)

(IV) Other modifications

e.g. modified Euler

$$w_0 = \alpha$$

$$w_{i+1} = w_i + \frac{h}{2} \left(f(t_i, w_i) + f(t_{i+1}, \tilde{w}_{i+1}) \right)$$

where

$$\tilde{w}_{i+1} = w_i + h f(t_i, w_i)$$